# Graph Surfaces Invariant by Parabolic Screw Motions with Constant Curvature in $\mathbb{H}^{2} \times \mathbb{R}$ 

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#### Abstract

In this work we study vertical graph surfaces invariant by parabolic screw motions with pitch $\ell>0$ and constant Gaussian curvature or constant extrinsic curvature in the product space $\mathbb{H}^{2} \times \mathbb{R}$. In particular, we determine flat and extrinsically flat graph surfaces in $\mathbb{H}^{2} \times \mathbb{R}$. We also obtain complete and non-complete vertical graph surfaces in $\mathbb{H}^{2} \times \mathbb{R}$ with negative constant Gaussian curvature and zero extrinsic curvature.


Keywords: Parabolic screw motion, graph surface, Gaussian curvature, extrinsic curvature, flat surface.
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## 1. Introduction

In $[12,17], H$. Rosenberg and $W$. Meeks studied minimal surfaces in $M^{2} \times \mathbb{R}$, where $M^{2}$ is a rounded sphere, a complete Riemannian surface with a metric of non-negative curvature, or $M^{2}=\mathbb{H}^{2}$, the hyperbolic plane. Since then, there has been a rapid growing interest in minimal surfaces and surfaces with constant mean curvature in $\mathbb{H}^{2} \times \mathbb{R}$ and $\mathbb{S}^{2} \times \mathbb{R}$, see for instance $[4,5,9,13,14,15,18,19,20]$. Also, surfaces in $\mathbb{H}^{2} \times \mathbb{R}$ and $\mathbb{S}^{2} \times \mathbb{R}$ with constant Gaussian curvature or constant extrinsic curvature have attracted many attention in the recent years, [1, 2, 3, 6, 7, 16].

In [1], J. A. Aldeo and et al. proved that there exists a unique complete surface of positive constant Gaussian curvature in $\mathbb{H}^{2} \times \mathbb{R}$ and a unique complete surface of positive constant curvature greater than 1 in $\mathbb{S}^{2} \times \mathbb{R}$, up to isometries of the ambient space. These complete surfaces are precisely the revolution surfaces. Also, they proved that there is no complete immersion of constant Gaussian curvature $K<-1$ into $\mathbb{H}^{2} \times \mathbb{R}$ and $\mathbb{S}^{2} \times \mathbb{R}$. In [2] J. A. Aldeo and et al. obtained some free boundary results for compact surfaces of positive constant Gaussian curvature in $\mathbb{H}^{2} \times \mathbb{R}$ and positive constant Gaussian curvature greater than 1 in $\mathbb{S}^{2} \times \mathbb{R}$.

In [7], J. M. Espinar and et al. studied complete surfaces with positive extrinsic curvature in $\mathbb{H}^{2} \times \mathbb{R}$ and $\mathbb{S}^{2} \times \mathbb{R}$, and they proved that every complete connected immersed surface with positive extrinsic curvature in $\mathbb{H}^{2} \times \mathbb{R}$ must be properly embedded, homeomorphic to a sphere or a plane. They also showed that only complete surfaces with constant extrinsic curvature in $\mathbb{H}^{2} \times \mathbb{R}$ and $\mathbb{S}^{2} \times \mathbb{R}$ are rotational sphere.
L. Belarbi [3] studied translation surfaces with constant extrinsic Gaussian curvature in the 3-dimensional Heisenberg group which are invariant under the 1-parameter groups of isometries.

In [16] R. Novais and P. D. Santos studied geometric characterizations of conformally flat and radially flat hypersurfaces in $\mathbb{S}^{n} \times \mathbb{R}$ and $\mathbb{H}^{n} \times \mathbb{R}$ are given by means of their extrinsic geometry, and in [6] Dillan and et al. classified minimal rotation hypersurfaces and flat rotation hypersurfaces in $\mathbb{S}^{2} \times \mathbb{R}$ and $\mathbb{H}^{2} \times \mathbb{R}$.

Screw motion surfaces with constant mean curvature in $\mathbb{H}^{2} \times \mathbb{R}$ and $\mathbb{S}^{2} \times \mathbb{R}$ were studied in [18, 19]. R. Sa Earp and E. Toubiana [19] obtained an explicit two parameter family of complete, embedded, simply connected, minimal screw motion surfaces in $\mathbb{H}^{2} \times \mathbb{R}$ with pitch $\ell$, and for $\ell=1$ each such surface has Gaussian curvature $K=-1$. In [18] R. Sa Earp studied complete minimal and surfaces with constant mean curvature invariant either by parabolic or by hyperbolic screw motions in $\mathbb{H}^{2} \times \mathbb{R}$. Later, Q . Cui and et al. [4] studied the geometric behaviors of hyperbolic and parabolic screw motions surfaces immersed in $\widetilde{P S L_{2}}(\mathbb{R}, \tau)$ with having

[^0]constant mean curvature, where $\widetilde{P S L_{2}}(\mathbb{R}, \tau)$ is a homogeneous simply connected 3-manifold having isometry group of dimension 4.

The isometries of $\mathbb{H}^{2}$ generate isometries in $\mathbb{H}^{2} \times \mathbb{R}$. In particular, a parabolic translation in $\mathbb{H}^{2}$ generates an isometry in $\mathbb{H}^{2} \times \mathbb{R}$ that is called a parabolic isometry. In this work we only consider the parabolic isometries, and the compositions of such isometries with vertical translations which are called parabolic helicoidal-type isometries. The surfaces invariant by this kind of helicoidal isometries is called the parabolic screw motion surfaces.

Motivated by the work [18] on the parabolic screw motion surfaces with constant mean curvature in $\mathbb{H}^{2} \times \mathbb{R}$, we study vertical graph surfaces invariant by the parabolic screw motions in $\mathbb{H}^{2} \times \mathbb{R}$ with constant Gaussian curvature or constant extrinsic curvature. We obtain the ordinary differential equations for the Gaussian curvature and extrinsic curvature of a graph surface $M(f)$ (invariant by the parabolic screw motion) in $\mathbb{H}^{2} \times \mathbb{R}$ for the function of the form $f(x, y)=v(y)+\ell x$, where $v(y)$ is a $\mathcal{C}^{2}$ function. We prove that if a vertical graph surface $M(f)$ in $\mathbb{H}^{2} \times \mathbb{R}$ for a function of the form $f(x, y)=u(x)+v(y)$ is extrinsically flat, then $u(x)=\ell x+c$, that is, $M(f)$ is a parabolic screw motion surface in $\mathbb{H}^{2} \times \mathbb{R}$, (see Sec. 3). Graph surfaces of the form $f(x, y)=u(x)+v(y)$ are also known as the translation surfaces in the literature. We determine graph surfaces $M(f)$ invariant by the parabolic screw motion (and also by parabolic translation) in $\mathbb{H}^{2} \times \mathbb{R}$ with constant Gaussian curvature $K$ and constant extrinsic curvature $K_{\text {ext }}$. We also obtain complete graph surfaces in $\mathbb{H}^{2} \times \mathbb{R}$ with negative constant Gaussian curvature and zero extrinsic curvature.

## 2. Preliminaries

Let $\mathbb{H}^{2}$ be the upper half-plane model $\mathbb{H}^{2}=\left\{(x, y) \in \mathbb{R}^{2} \mid y>0\right\}$ of the hyperbolic plane equipped with the hyperbolic metric $g=\frac{d x^{2}+d y^{2}}{y^{2}}$ of constant curvature -1 . We consider the product space $\widetilde{M}^{3}=\mathbb{H}^{2} \times \mathbb{R}$ with coordinates $(x, y, t)$ and the metric $\tilde{g}=g+d t^{2}$.

Let $\widetilde{\nabla}$ denote the Riemannian connection of $\widetilde{M}^{3}$. The Riemannian curvature tensor $\widetilde{R}$ of $\widetilde{M}^{3}$ is given by

$$
\widetilde{R}(X, Y) Z=\widetilde{\nabla}_{X} \widetilde{\nabla}_{Y} Z-\widetilde{\nabla}_{Y} \widetilde{\nabla}_{X} Z-\widetilde{\nabla}_{[X, Y]} Z
$$

where $X, Y$, and $Z$ are tangent vector fields on $\widetilde{M}^{3}$. If $X, Y \in T_{p} \widetilde{M}^{3}$ at a point $p \in \widetilde{M}^{3}$, then the sectional curvature of $\widetilde{M}^{3}$ for the plane spanned by $X$ and $Y$ in $T_{p} \widetilde{M}^{3}$ is

$$
\widetilde{K}(X, Y)=-\frac{\widetilde{g}(\widetilde{R}(X, Y) X, Y)}{\widetilde{g}(X, X) \widetilde{g}(Y, Y)-\widetilde{g}(X, Y) \widetilde{g}(X, Y)}
$$

Let $M$ be a regular surface in $\widetilde{M}$. Then, the Gauss equation of $M$ in $\widetilde{M}^{3}$ is given by

$$
\begin{equation*}
\tilde{g}(\widetilde{R}(X, Y) Z, W)=\tilde{g}(R(X, Y) Z, W)+\tilde{g}(h(X, Z), h(Y, W))-\tilde{g}(h(Y, Z), h(X, W)) \tag{2.1}
\end{equation*}
$$

where $X, Y, Z, W \in T M, h$ is the second fundamental form, and $R$ is the Riemannian curvature tensor of $M$.
Let $\partial_{x}=\frac{\partial}{\partial x}, \partial_{y}=\frac{\partial}{\partial y}, \partial_{t}=\frac{\partial}{\partial t}$ denote coordinate vector fields on $\widetilde{M^{3}}$. The vectors $E_{1}=y \partial_{x}, E_{2}=y \partial_{y}, E_{3}=\partial_{t}$ form an orthonormal frame on $\widetilde{M^{3}}$, and in this frame, non-zero covariant derivatives of $\widetilde{M^{3}}$ are

$$
\begin{equation*}
\widetilde{\nabla}_{E_{1}} E_{1}=E_{2}, \widetilde{\nabla}_{E_{1}} E_{2}=-E_{1} \tag{2.2}
\end{equation*}
$$

### 2.1. Graph surfaces

Let $\Omega$ be an open connected region in the hyperbolic plane $\mathbb{H}^{2}$, and let $f: \Omega \rightarrow \mathbb{R}$ be a $\mathcal{C}^{2}$ function on $\Omega$. A vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ is a set

$$
M(f)=\left\{(x, y, f(x, y)) \in \mathbb{H}^{2} \times \mathbb{R} \mid(x, y) \in \Omega\right\}
$$

and it is called entire if $\Omega=\mathbb{H}^{2}$.
Considering the natural parameterization $\varphi(x, y)=(x, y, f(x, y))$ of $M(f)$ in $\mathbb{H}^{2} \times \mathbb{R}$, the coordinate vector fields of the graph surface $M(f)$ are

$$
\begin{equation*}
\varphi_{x}(x, y)=\frac{1}{y} E_{1}+f_{x} E_{3} \quad \text { and } \quad \varphi_{y}(x, y)=\frac{1}{y} E_{2}+f_{y} E_{3} \tag{2.3}
\end{equation*}
$$

and the coefficients of the first fundamental form induced by $\varphi$ are

$$
\begin{equation*}
E=\tilde{g}\left(\varphi_{x}, \varphi_{x}\right)=\frac{1}{y^{2}}+f_{x}^{2}, \quad F=\tilde{g}\left(\varphi_{x}, \varphi_{y}\right)=f_{x} f_{y}, \quad G=\tilde{g}\left(\varphi_{y}, \varphi_{y}\right)=\frac{1}{y^{2}}+f_{y}^{2} . \tag{2.4}
\end{equation*}
$$

Then, the determinant of the induced metric on $M(f)$ by $\varphi$ is obtained as

$$
\begin{equation*}
E G-F^{2}=\frac{1+y^{2}\left(f_{x}^{2}+f_{y}^{2}\right)}{y^{4}} \tag{2.5}
\end{equation*}
$$

and the graph surface $M(f)$ is regular, or $\varphi$ is an immersion if $E G-F^{2}>0$.
We put $W=\sqrt{1+y^{2}\left(f_{x}^{2}+f_{y}^{2}\right)}$. Then, the normal vector to $M(f)$ in $\widetilde{M^{3}}$ is written as

$$
n=\frac{1}{W}\left(-y f_{x} E_{1}-y f_{y} E_{2}+E_{3}\right)
$$

When we evaluate the covariant derivatives of the tangent vector fields of $\varphi$ we get

$$
\tilde{\nabla}_{\varphi_{x}} \varphi_{x}=\frac{1}{y^{2}} E_{2}+f_{x x} E_{3}, \tilde{\nabla}_{\varphi_{x}} \varphi_{y}=-\frac{1}{y^{2}} E_{1}+f_{x y} E_{3}, \tilde{\nabla}_{\varphi_{y}} \varphi_{y}=-\frac{1}{y^{2}} E_{2}+f_{y y} E_{3},
$$

and hence, we obtain the coefficients of the second fundamental form in the local coordinates as follows:

$$
\begin{equation*}
L=\tilde{g}\left(\widetilde{\nabla}_{\varphi_{x}} \varphi_{x}, n\right)=\frac{y f_{x x}-f_{y}}{y W}, \quad M=\tilde{g}\left(\widetilde{\nabla}_{\varphi_{x}} \varphi_{y}, n\right)=\frac{y f_{x y}+f_{x}}{y W}, \quad N=\tilde{g}\left(\widetilde{\nabla}_{\varphi_{y}} \varphi_{y}, n\right)=\frac{y f_{y y}+f_{y}}{y W} . \tag{2.6}
\end{equation*}
$$

It is known that for surfaces in $\mathbb{R}^{3}$, the Gaussian (intrinsic) curvature $K$ and extrinsic curvature $K_{\text {ext }}$ are equal. In the following we see that the intrinsic and extrinsic curvatures differ by the sectional curvature in $\mathbb{H}^{2} \times \mathbb{R}$.

Let $M(f)$ be a vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ defined by a $\mathcal{C}^{2}$ function $f$ on an open connected region $\Omega \subset \mathbb{H}^{2}$. By using (2.3), we obtain that $\widetilde{R}\left(\varphi_{x}, \varphi_{y}\right) \varphi_{x}=\frac{1}{y^{3}} E_{2}$. Then, the sectional curvature of $\mathbb{H}^{2} \times \mathbb{R}$ for the section determined by the vectors $\varphi_{x}$ and $\varphi_{y}$ is

$$
\widetilde{K}\left(\varphi_{x}, \varphi_{y}\right)=-\frac{\widetilde{g}\left(\widetilde{R}\left(\varphi_{x}, \varphi_{y}\right) \varphi_{x}, \varphi_{y}\right)}{E G-F^{2}}=-\frac{1}{y^{4}\left(E G-F^{2}\right)}=-\frac{1}{1+y^{2}\left(f_{x}^{2}+f_{y}^{2}\right)}
$$

which is bounded i.e. $-1 \leq \widetilde{K}<0$, and the equality case holds if and only if $f(x, y)=c$, where $c$ is a constant. Using (2.2) and (2.3), from the Gauss equation (2.1) we have the Gaussian curvature $K$ of $M(f)$ as

$$
K=K\left(\varphi_{x}, \varphi_{y}\right)=-\frac{\widetilde{g}\left(R\left(\varphi_{x}, \varphi_{y}\right) \varphi_{x}, \varphi_{y}\right)}{E G-F^{2}}=\widetilde{K}+K_{e x t},
$$

where $K_{\text {ext }}$ is the extrinsic curvature of $M(f)$, and it is defined by $K_{\text {ext }}=\left(L N-M^{2}\right) /\left(E G-F^{2}\right)$. Thus, the Gaussian curvature $K$ is given by

$$
K=\frac{1}{E G-F^{2}}\left(-\frac{1}{y^{4}}+\left(L N-M^{2}\right)\right) .
$$

A vertical graph surface $M(f)$ in $\mathbb{H}^{2} \times \mathbb{R}$ is called intrinsically flat (resp., extrinsically flat) if $K=0$ (resp., $\left.K_{\text {ext }}=0\right)$ on $M(f)$.

Using (2.6), the Gaussian curvature and extrinsic curvature of $M(f)$ are obtained, respectively, as

$$
\begin{equation*}
K=\frac{y^{2}\left[\left(y f_{x x}-f_{y}\right)\left(y f_{y y}+f_{y}\right)-\left(y f_{x y}+f_{x}\right)^{2}\right]-y^{2}\left(f_{x}^{2}+f_{y}^{2}\right)-1}{\left[1+y^{2}\left(f_{x}^{2}+f_{y}^{2}\right)\right]^{2}} \tag{2.7}
\end{equation*}
$$

and

$$
\begin{equation*}
K_{e x t}=\frac{y^{2}\left[\left(y f_{x x}-f_{y}\right)\left(y f_{y y}+f_{y}\right)-\left(y f_{x y}+f_{x}\right)^{2}\right]}{\left[1+y^{2}\left(f_{x}^{2}+f_{y}^{2}\right)\right]^{2}} \tag{2.8}
\end{equation*}
$$

Also, since

$$
\begin{equation*}
-1 \leq \widetilde{K}=K-K_{e x t}=-\frac{1}{1+y^{2}\left(f_{x}^{2}+f_{y}^{2}\right)}<0 \tag{2.9}
\end{equation*}
$$

we have that

1) if $M(f)$ has constant extrinsic curvature $K_{e x t}$, then the Gaussian curvature $K$ is bounded, i.e., $K_{e x t}-1 \leq$ $K<K_{e x t}$;
2) if $M(f)$ has constant Gaussian curvature $K$, then the extrinsic curvature $K_{\text {ext }}$ is bounded, i.e., $K<K_{\text {ext }} \leq$ $K+1$.

By using (2.7) and (2.8), we have the followings:
Proposition 2.1. Let $M(f)$ be a vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ for a $\mathcal{C}^{2}$ function $f: \Omega \subset \mathbb{H}^{2} \rightarrow \mathbb{R}$ defined on an open connected region $\Omega$. Then, $M(f)$ is an intrinsically flat surface in $\mathbb{H}^{2} \times \mathbb{R}$ if and only if $f(x, y)$ satisfies

$$
\begin{equation*}
y^{2}\left[\left(y f_{x x}-f_{y}\right)\left(y f_{y y}+f_{y}\right)-\left(y f_{x y}+f_{x}\right)^{2}\right]-y^{2}\left(f_{x}^{2}+f_{y}^{2}\right)-1=0 \tag{2.10}
\end{equation*}
$$

Proposition 2.2. Let $M(f)$ be a vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ for a $\mathcal{C}^{2}$ function $f: \Omega \subset \mathbb{H}^{2} \rightarrow \mathbb{R}$ defined on an open connected region $\Omega$. Then, $M(f)$ is an extrinsically flat surface in $\mathbb{H}^{2} \times \mathbb{R}$ if and only if $f(x, y)$ satisfies

$$
\begin{equation*}
\left(y f_{x x}-f_{y}\right)\left(y f_{y y}+f_{y}\right)-\left(y f_{x y}+f_{x}\right)^{2}=0 . \tag{2.11}
\end{equation*}
$$

Proposition 2.3. Let $v \in \mathcal{C}^{2}$ be defined on an open interval of $\mathbb{R}$. Let $M(f)$ be a vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ for a function of the form $f(x, y)=v(y)+\ell x$, that is, $M(f)$ is invariant by the parabolic screw motion with pitch $\ell>0$. Then, the Gaussian curvature $K$ and the extrinsic curvature $K_{\text {ext }}$ are given, respectively, by

$$
\begin{equation*}
K=\frac{y}{2} \frac{d}{d y}\left(\frac{1}{1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)}\right)-\frac{1}{1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)} \tag{2.12}
\end{equation*}
$$

and

$$
\begin{equation*}
K_{e x t}=\frac{y}{2} \frac{d}{d y}\left(\frac{1}{1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)}\right) \tag{2.13}
\end{equation*}
$$

Now, by using (2.9) we prove the following theorem.
Theorem 2.1. Let $M(f)$ be a vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ for a $\mathcal{C}^{2}$ function $f(x, y)$ defined on some open connected region $\Omega \subset \mathbb{H}^{2}$. Then, the difference between the extrinsic curvature $K_{\text {ext }}$ and the Gaussian curvature $K$ is a constant if and only if the function $f$ is given by

$$
\begin{equation*}
f(x, y)=\ell x \mp\left(\sqrt{b^{2}-\ell^{2} y^{2}}+b \ln \left(\frac{y}{b+\sqrt{b^{2}-\ell^{2} y^{2}}}\right)\right)+c \tag{2.14}
\end{equation*}
$$

defined on the region $\Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, 0<y<\frac{b}{\ell}\right.\right\}$, where $\ell, b, c \in \mathbb{R}$ with $\ell, b>0$. Moreover, $M(f)$ has both $K_{\text {ext }}$ and $K$ constant, that is, $K_{e x t}=0$ and $K=-1 /\left(1+b^{2}\right)$, and it is invariant by the parabolic screw motion with pitch $\ell$.

Proof. Let $M(f)$ be a vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ for a $\mathcal{C}^{2}$ function $f(x, y)$ defined on some open connected region $\Omega \subset \mathbb{H}^{2}$. From (2.9), we have $0<K_{\text {ext }}-K \leq 1$, and $K_{\text {ext }}-K$ is a constant if and only if $f(x, y)$ satisfies

$$
f_{x}^{2}+f_{y}^{2}=\frac{b^{2}}{y^{2}}
$$

where $b=\sqrt{\frac{1}{K_{\text {ext }}-K}-1}$. The complete solution of this partial differential equation is of the form

$$
f(x, y)=\ell x \mp \int \frac{\sqrt{b^{2}-\ell^{2} y^{2}}}{y} d y+c
$$

for $0<y<b / \ell$, where $\ell$ and $c$ are integration constants with $\ell>0$. By integration we obtain (2.14).
Let $b$ be a positive constant. The function $f(x, y)$ given by (2.14) is of the form $f(x, y)=\ell x \mp v(y)$ with $v^{\prime}(y)=\frac{\sqrt{b^{2}-\ell^{2} y^{2}}}{y}$. It can be seen easily that $1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)$ is a constant. Thus, from (2.12) and (2.13) we have $K=-1 /\left(1+b^{2}\right)$ and $K_{\text {ext }}=0$, respectively. Also, for $\ell>0$ the form of $f$ means that $M(f)$ is a parabolic screw motion surface in $\mathbb{H}^{2} \times \mathbb{R}$ with pitch $\ell$.

### 2.2. Parabolic screw motion surfaces

Parabolic and hyperbolic screw motion surfaces in $\mathbb{H}^{2} \times \mathbb{R}$ were studied in [4, 18]. For the definition of parabolic screw motion surfaces we follow [4]. We will use helicoidal-type isometries in $\mathbb{H}^{2} \times \mathbb{R}$ which are the composition of isometries of $\mathbb{H}^{2}$ together with vertical translation in a proportional way. Let $\delta$ be the group of parabolic isometries in the half-plane $\mathbb{H}^{2}$, that is, the parabolic translations given by $T(x, y)=(x+c, y), c \in \mathbb{R}$. This group generates helicoidal-type isometries in $\mathbb{H}^{2} \times \mathbb{R}$, that is, the helicoidal isometries $\Gamma_{\ell}$ of pitch $\ell>0$, generated in $\mathbb{H}^{2} \times \mathbb{R}$ are given by $\widetilde{F}(x, y, t)=(T(x, y), t+\ell c)$. More precisely, for a fixed point $\left(x_{0}, y_{0}, t_{0}\right)$, it is given by

$$
\Gamma_{\ell}\left(x_{0}, y_{0}, t_{0}\right)=\left\{\left(x_{0}+c, y_{0}, t_{0}+c \ell\right) \mid c \in \mathbb{R}\right\} \subset \mathbb{H}^{2} \times \mathbb{R}
$$

The surfaces invariant by this helicoidal isometry will be called the parabolic screw motion surfaces. If $\ell=0$, we have surfaces invariant by parabolic translations.

In order to obtain a surface invariant by the parabolic screw motion, we consider a curve $\gamma=(0, y, v(y))$ in the $y t$-plane which is locally the graph of a function $v \in \mathcal{C}^{2}$ defined an open interval of $\mathbb{R}$. The surface $\Gamma_{\ell}(\gamma)$ which is invariant by this one-parameter group of helicoidal-type isometries generated by the curve $\gamma$ can therefore be parameterized by

$$
\varphi(x, y)=(x, y, v(y)+\ell x)
$$

which is a vertical graph surface $M(f)$ defined by a function of the form $f(x, y)=v(y)+\ell x$. In the literature, a surface defined by $\varphi(x, y)=(x, y, u(x)+v(y))$ is also known as a translation surface, for instance, see $[8,11,10]$ and references therein.

## 3. Flat and Extrinsically Flat Surfaces in $\mathbb{H}^{2} \times \mathbb{R}$

In this section we obtain intrinsically flat and extrinsically flat vertical graph surfaces invariant by the parabolic screw motions in $\mathbb{H}^{2} \times \mathbb{R}$.

Considering (2.7), (2.8), and $L, M, N$ in (2.6), for planes immersed in $\mathbb{H}^{2} \times \mathbb{R}$ we have
Proposition 3.1. Let $f(x, y)=a x+b y+c$, where $a, b, c \in \mathbb{R}$. Then, the vertical graph surface $M(f)$ in $\mathbb{H}^{2} \times \mathbb{R}$ is extrinsically flat if and only if $f(x, y)=c$. The graph surface $M(f)$ for $f(x, y)=c$ is an entire, complete, and totally geodesic surface invariant by the parabolic screw motions in $\mathbb{H}^{2} \times \mathbb{R}$ with the intrinsic Gaussian curvature $K=-1$.

For the vertical graph surfaces in $\mathbb{H}^{2} \times \mathbb{R}$ for the function of the form $f(x, y)=u(x)+v(y)$ we have
Theorem 3.1. Let $M(f)$ be a vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ for a $\mathcal{C}^{2}$ function of the form $f(x, y)=u(x)+v(y)$ defined on some open connected region $\Omega \subset \mathbb{H}^{2}$.Then, $M(f)$ is extrinsically flat if and only if

$$
\begin{equation*}
u(x)=\ell x+c \quad \text { and } \quad v(y)=\sqrt{b^{2}-\ell^{2} y^{2}}+b \ln \left(\frac{y}{b+\sqrt{b^{2}-\ell^{2} y^{2}}}\right) \tag{3.1}
\end{equation*}
$$

on the region $\Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, 0<y<\frac{b}{\ell}\right.\right\}$, where $\ell, b, c \in \mathbb{R}$ with $\ell, b>0$. This surface $M(f)$ is invariant by the parabolic screw motion with pitch $\ell$ and constant Gaussian curvature $K=-1 /\left(1+b^{2}\right)$.
Proof. Let $M(f)$ be a vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ for a $\mathcal{C}^{2}$ function of the form $f(x, y)=u(x)+v(y)$. Then, the graph surface $M(f)$ is extrinsically flat if and only if the function $f$ holds (2.11). That is, for $f(x, y)=u(x)+v(y)$, equation (2.11) becomes

$$
\begin{equation*}
u^{\prime \prime}(x)-\frac{1}{y\left(v^{\prime}+y v^{\prime \prime}\right)} u^{\prime 2}(x)-\frac{v^{\prime}}{y}=0 \tag{3.2}
\end{equation*}
$$

This is a differential equation of the form $u^{\prime \prime}(x)+\psi_{1}(y) u^{\prime 2}(x)+\psi_{2}(y)=0$. Since $\psi_{1}$ and $\psi_{2}$ are functions of $y$, if $u^{\prime \prime}(x) \neq 0$, then the solution of (3.2) does not define $u$ as a function of $x$, and hence there is no solution of (3.2) unless $u^{\prime \prime}(x)=0$. So, we have $u^{\prime \prime}(x)=0$ which implies that $u(x)=\ell x+c, \ell \neq 0, c \in \mathbb{R}$. Note that this result can also be followed by taking the derivative of (3.2) with respect to $y$. For $u(x)=\ell x+c$, we have from (3.2) that $v^{\prime} v^{\prime \prime}+\frac{v^{\prime 2}}{y}+\frac{\ell^{2}}{y}=0$. The solution of this differential equation gives

$$
v(y)=\mp \int \frac{\sqrt{b^{2}-\ell^{2} y^{2}}}{y} d y+c
$$

where $b>0$ and $c$ are integration constants, and $0<y<b / \ell$. By integrating the last integral and using a vertical translation and symmetry about the $x y$-plane we have (3.1). Also, from (2.12) we obtain that the Gauss curvature $K=-1 /\left(1+b^{2}\right)$. For the obtained functions $u(x)$ and $v(y), M(f)$ is a parabolic screw motion surface in $\mathbb{H}^{2} \times \mathbb{R}$ with pitch $\ell>0$.

Remark 3.1. Up to a vertical translation, the vertical graph surfaces $M(f)$ in $\mathbb{H}^{2} \times \mathbb{R}$ for $f(x, y)=v(y)+\ell x$ with $v(y)$ defined by the second function in (3.1) are the only surfaces invariant by the parabolic screw motion in $\mathbb{H}^{2} \times \mathbb{R}$ with constant Gaussian curvature $K$ and constant extrinsic curvature $K_{\text {ext }}$.

Now, by taking $\ell=0$ in (3.1), the vertical graph surface $M(f)$ for $f(x, y)=v(y)$ is a cylinder parallel to the $x$-axis immersed in $\mathbb{H}^{2} \times \mathbb{R}$. Such a surface is invariant by the parabolic translation. Thus, we have

Corollary 3.1. Let $v \in \mathcal{C}^{2}$ be defined an open interval of $\mathbb{R}$. Up to a vertical translation and symmetry about the xyplane, a vertical graph surface $M(f)$ in $\mathbb{H}^{2} \times \mathbb{R}$ for a function of the form $f(x, y)=v(y)$ is extrinsically flat if and only if $f(x, y)=b \ln y, b \in \mathbb{R}_{+}$. Also, $M(f)$ is an entire surface invariant by the parabolic translation in $\mathbb{H}^{2} \times \mathbb{R}$ with constant Gaussian curvature $K=-1 /\left(b^{2}+1\right)$.

Theorem 3.2. Let $M(f)$ be a vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ for a $\mathcal{C}^{2}$ function of the form $f(x, y)=v(y)+\ell x$ on some open connected region $\Omega \subset \mathbb{H}^{2}$, where $\ell$ is a positive constant, that is, $M(f)$ is a parabolic screw motion surface in $\mathbb{H}^{2} \times \mathbb{R}$ with pitch $\ell$. Then, $M(f)$ is intrinsically flat if and only if

$$
\begin{equation*}
f(x, y)=\ell x \pm \int \frac{\sqrt{b-y^{2}-\ell^{2} y^{4}}}{y^{2}} d y \tag{3.3}
\end{equation*}
$$

on the region $\Omega=\left\{(x, y) \in \mathbb{H}^{2} \mid 0<y<\sqrt{-1+\sqrt{4 \ell^{2} b+1}} / \sqrt{2} \ell\right\}$, where $b>0$ is an integration constant. Also, the extrinsic curvature $K_{\text {ext }}$ is given by $K_{\text {ext }}=y^{2} / b$.

Proof. Let $f(x, y)=v(y)+\ell x$. Then, from (2.12) a vertical graph surface $M(f)$ has zero Gaussian curvature, $K=0$, if and only if the function $v(y)$ satisfies the equation

$$
\begin{equation*}
\frac{y}{2} \frac{d}{d v}\left(\frac{1}{1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)}\right)-\frac{1}{1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)}=0 \tag{3.4}
\end{equation*}
$$

Now we put $q(y)=1 /\left(1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)\right)$. Then, we have $y q^{\prime}(y)-2 q(y)=0$, and its solution yields $q(y)=y^{2} / b$, where $b$ is a non-zero integration constant. Therefore, for this $q(y)$, solving $q(y)=1 /\left(1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)\right)$ for $v(y)$, and using a vertical translation, we obtain (3.3) for $b>0$, and from (3.3) we have the region $\Omega$ in the theorem.

Now, from (2.13) and (3.4) we get $K_{e x t}=\frac{1}{1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)}=q(y)=\frac{y^{2}}{b}$.

By taking $\ell=0$, integrating (3.3) and also considering a vertical translation and symmetry about the $x y$-plane, we have

Corollary 3.2. Let $M(f)$ be a vertical graph surface (an immersed cylinder) in $\mathbb{H}^{2} \times \mathbb{R}$ for a $\mathcal{C}^{2}$ function of the form $f(x, y)=v(y)$ on some open connected region $\Omega \subset \mathbb{H}^{2}$, that is, $M(f)$ is invariant by the parabolic translation. Then, $M(f)$ is intrinsically flat if and only if

$$
\begin{equation*}
f(x, y)=\arcsin \left(\frac{y}{\sqrt{b}}\right)+\frac{\sqrt{b-y^{2}}}{y} \tag{3.5}
\end{equation*}
$$

on the region $\Omega=\left\{(x, y) \in \mathbb{H}^{2} \mid 0<y<\sqrt{b}\right\}$, where $b$ is a positive constant.

## 4. Surfaces with non-zero constant curvature

In this section we study vertical graph surfaces invariant by parabolic screw motions in $\mathbb{H}^{2} \times \mathbb{R}$ with non-zero constant Gaussian curvature, and with non-zero constant extrinsic curvature.

### 4.1. Surfaces with non-zero constant extrinsic curvature

Theorem 4.1. Let $M(f)$ be a vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ for a $\mathcal{C}^{2}$ function of the form $f(x, y)=v(y)+\ell x$ on some open connected region $\Omega \subset \mathbb{H}^{2}$, where $\ell$ is a positive constant, that is, $M(f)$ is a parabolic screw motion surface with pitch $\ell$. Then, $M(f)$ has non-zero constant extrinsic curvature $K_{\text {ext }}$ if and only if

$$
\begin{equation*}
f(x, y)=\ell x \pm \int \frac{1}{y} \sqrt{\frac{1-\left(1+\ell^{2} y^{2}\right)\left(b+2 K_{e x t} \ln y\right)}{b+2 K_{e x t} \ln y}} d y \tag{4.1}
\end{equation*}
$$

on the open connected region $\Omega=\left\{(x, y) \in \mathbb{H}^{2} \mid 0<b+2 K_{\text {ext }} \ln y<1\right.$ and $\left.\left(1+\ell^{2} y^{2}\right)\left(b+2 K_{\text {ext }} \ln y\right)<1\right\}$.
Proof. Let $M(f)$ be a vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ for $f(x, y)=v(y)+\ell x$. Then, $M(f)$ has non-zero constant extrinsic curvature $K_{\text {ext }}$ if and only if

$$
\frac{d}{d v}\left(\frac{1}{1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)}\right)=\frac{2 K_{e x t}}{y}
$$

because of (2.13), which can be written as $1 /\left(1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)\right)=b+2 K_{e x t} \ln y$, where $b \in \mathbb{R}$ and $0<b+$ $2 K_{\text {ext }} \ln y<1$. When we solve this equation for $v(y)$ and using a vertical translation, we obtain (4.1).

By taking $\ell=0$ and integrating (4.1) we have
Corollary 4.1. Let $M(f)$ be a vertical graph surface, (an immersed cylinder) in $\mathbb{H}^{2} \times \mathbb{R}$ for a $\mathcal{C}^{2}$ function of the form $f(x, y)=v(y)$ on some open connected region $\Omega \subset \mathbb{H}^{2}$. Then, the graph surface $M(f)$ invariant by the parabolic translation has non-zero constant extrinsic curvature $K_{\text {ext }}$ if and only if

$$
\begin{equation*}
f(x, y)=\frac{1}{2 K_{e x t}}\left(\sqrt{\left(1-b-2 K_{e x t} \ln y\right)\left(b+2 K_{e x t} \ln y\right)}-\arctan \sqrt{\frac{1-b-2 K_{e x t} \ln y}{b+2 K_{e x t} \ln y}}\right) \tag{4.2}
\end{equation*}
$$

on the open connected region $\Omega=\left\{(x, y) \in \mathbb{H}^{2} \mid e^{-b / 2 K_{\text {ext }}}<y<e^{(1-b) / 2 K_{\text {ext }}}\right\}$ for $K_{\text {ext }}>0$, and $\Omega=\{(x, y) \in$ $\left.\mathbb{H}^{2} \mid e^{(1-b) / 2 K_{e x t}}<y<e^{-b / 2 K_{\text {ext }}}\right\}$ for $K_{\text {ext }}<0$, where $b$ is a constant.

### 4.2. Surfaces with non-zero Constant Gaussian Curvature

Let $f(x, y)=a x+b y+c$, where $a, b, c \in \mathbb{R}$. Then, from (2.7) the Gaussian curvature of the vertical graph surface $M(f)$ is obtained as

$$
K=\frac{-1-2 y^{2}\left(a^{2}+b^{2}\right)}{\left[1+y^{2}\left(a^{2}+b^{2}\right)\right]^{2}}
$$

from which we can state
Proposition 4.1. Let $f(x, y)=a x+b y+c$, where $a, b, c \in \mathbb{R}$. Then, the vertical graph surface $M(f)$ in $\mathbb{H}^{2} \times \mathbb{R}$ has constant negative Gaussian curvature $K=-1$ if and only if $f(x, y)=c$. The graph surface $M(f)$ invariant by the parabolic screw motions is an entire, totally geodesic and complete surface in $\mathbb{H}^{2} \times \mathbb{R}$ with $K=-1$.

Theorem 4.2. Let $M(f)$ be a vertical graph surface in $\mathbb{H}^{2} \times \mathbb{R}$ for a $\mathcal{C}^{2}$ function of the form $f(x, y)=v(y)+\ell x$ on some open connected region $\Omega \subset \mathbb{H}^{2}$, where $\ell$ is a positive constant, that is, $M(f)$ is a parabolic screw motion surface with pitch $\ell$. Then, $M(f)$ has non-zero constant Gaussian curvature $K$ if and only if the function $v(y)$ is given by

$$
\begin{equation*}
f(x, y)=\ell x \pm \int \frac{1}{y} \sqrt{\frac{1-\left(\ell^{2} y^{2}+1\right)\left(b y^{2}-K\right)}{b y^{2}-K}} d y \tag{4.3}
\end{equation*}
$$

where $b$ and $K$ are non-zero constants; and the region $\Omega$ is given as follows:

1) for $K>0, \Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, \sqrt{\frac{K}{b}}<y<\sqrt{\frac{-\left(b-\ell^{2} K\right)+\sqrt{\left(b-\ell^{2} K\right)^{2}+4 \ell^{2} b(1+K)}}{2 b \ell^{2}}}\right.\right\}$ if $b>0$;
2) for $-1<K<0, \Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, 0<y<\sqrt{\frac{-\left(b-\ell^{2} K\right)+\sqrt{\left(b-\ell^{2} K\right)^{2}+4 \ell^{2} b(1+K)}}{2 b \ell^{2}}}\right.\right\}$ if $b>0$, or
$\Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, \sqrt{\frac{b-\ell^{2} K+\sqrt{\left(b-\ell^{2} K\right)^{2}+4 \ell^{2} b(1+K)}}{2(-b) \ell^{2}}}<y<\sqrt{\frac{K}{b}}\right.\right\}$ if $\ell^{2}(2 \sqrt{K+1}-K-2)<b<0 ;$
3) for $K=-1, \Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, \sqrt{\frac{\ell^{2}+b}{-b \ell^{2}}}<y<\frac{1}{\sqrt{-b}}\right.\right\}$ if $-\ell^{2} \leq b<0$, or

$$
\Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, 0<y<\frac{1}{\sqrt{-b}}\right.\right\} \text { if } b<-\ell^{2} ;
$$

4) for $K<-1, \Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, \sqrt{\frac{b-\ell^{2} K+\sqrt{\left(b-\ell^{2} K_{0}\right)^{2}+4 \ell^{2} b(1+K)}}{2(-b) \ell^{2}}}<y<\sqrt{\frac{K}{b}}\right.\right\}$ if $b<0$.

Proof. Let $f(x, y)=\ell x+v(y)$. A vertical graph surface $M(f)$ has non-zero constant Gaussian curvature $K$ if and only if the function $v(y)$ is a solution of (2.12).
Now, if we put $q(y)=1 /\left(1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)\right)$, then the equation (2.12) turns to $q^{\prime}(y)-\frac{2}{y} q(y)=\frac{2 K}{y}$, and its solution yields $q(y)=b y^{2}-K$, where $b$ is an integration constant. Therefore, for this $q(y)$ solving $q(y)=1 /\left(1+y^{2}\left(v^{\prime 2}+\ell^{2}\right)\right)$ for $v(y)$ and considering a vertical translation, we obtain (4.3). Also, from (2.5) we obtain $E G-F^{2}=\frac{1}{y^{4}\left(b y^{2}-K\right)}$ that implies $b y^{2}-K>0$ as $M(f)$ is regular. From (4.3), the function $v(y)$ is defined if $0<\left(\ell^{2} y^{2}+1\right)\left(b y^{2}-K\right)<1$. Analyzing these inequalities for the values of $\ell, b$, and $K$, we obtain the regions $\Omega$ stated in the theorem.

Let $b=0$ in (4.3). Then, from $E G-F^{2}=\frac{1}{y^{4}(-K)}$, the surface $M(f)$ is regular if $K<0$. Also, we have $K_{e x t}=0$ for the function $v(y)$ given by (4.3) because of Theorem 3.1. Thus, by integrating (4.3) and using (2.9) we have

Corollary 4.2. The vertical graph surface $M(f)$ invariant by a parabolic screw motion has negative constant Gaussian curvature with $-1<K<0$ for the function

$$
\begin{equation*}
f(x, y)=\ell x \pm\left(\sqrt{\lambda^{2}-\ell^{2} y^{2}}+\lambda \ln \left(\frac{y}{\lambda+\sqrt{\lambda^{2}-\ell^{2} y^{2}}}\right)\right) \tag{4.4}
\end{equation*}
$$

defined on the region $\Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, 0<y<\frac{\lambda}{\ell}\right.\right\}$, where $\lambda=\sqrt{\frac{1+K}{-K}}$.
Now, by taking $\ell=0$ in (4.3), and considering a vertical translation and symmetry about the $x y$-plane, we have

Corollary 4.3. Let $M(f)$ be a graph surface (immersed cylinder) in $\mathbb{H}^{2} \times \mathbb{R}$ for a $\mathcal{C}^{2}$ function of the form $f(x, y)=v(y)$ on some open connected region $\Omega \subset \mathbb{H}^{2}$. Then, $M(f)$ invariant by the parabolic translation has non-zero constant Gaussian curvature $K$ if and only if the function $f$ is given by
1)

$$
\begin{equation*}
f(x, y)=\sqrt{\frac{1+K}{K}} \tan ^{-1}\left(\sqrt{\frac{1+K}{K}} \sqrt{\frac{b y^{2}-K}{1+K-b y^{2}}}\right)-\sin ^{-1} \sqrt{b y^{2}-K} \tag{4.5}
\end{equation*}
$$

defined on the region $\Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, \sqrt{\frac{K}{b}}<y<\sqrt{\frac{1+K}{b}}\right.\right\}$ for $K>0$ and $b>0$, or
$\Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, \sqrt{\frac{1+K}{b}}<y<\sqrt{\frac{K}{b}}\right.\right\}$ for $K \leq-1$ and $b<0 ;$
2)

$$
\begin{equation*}
f(x, y)=\sqrt{\frac{1+K}{-K}} \tanh ^{-1}\left(\sqrt{\frac{1+K}{-K}} \sqrt{\frac{b y^{2}-K}{1+K-b y^{2}}}\right)+\sin ^{-1} \sqrt{b y^{2}-K} \tag{4.6}
\end{equation*}
$$

defined on the region $\Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, 0<y<\sqrt{\frac{1+K}{b}}\right.\right\}$ for $-1<K<0$ and $b>0$, or
$\Omega=\left\{(x, y) \in \mathbb{H}^{2} \left\lvert\, 0<y<\sqrt{\frac{K}{b}}\right.\right\}$ for $-1 \leq K<0$ and $b<0 ;$
3) $f(x, y)=\sqrt{\frac{1+K}{-K}} \ln y$ defined on the region $\Omega=\mathbb{H}^{2}$ for $-1<K<0$ and $b=0$.

When we evaluate the geodesics of the surface $M(f)$ for the function $f(x, y)=a \ln y$ on the region $\Omega=\mathbb{H}^{2}$ we obtain the geodesics parametrized by arc length parameter as follows:

$$
\gamma_{1}(s)=\left(x_{0}, y_{0} e^{s / \sqrt{1+a^{2}}}, a \ln \left(y_{0} e^{s / \sqrt{1+a^{2}}}\right)\right), s \in \mathbb{R}
$$

and

$$
\gamma_{2}(s)=\left(\frac{\sqrt{1+a^{2}}}{x_{0}} \tanh \left(\frac{s-y_{0}}{\sqrt{1+a^{2}}}\right)+x_{1}, \frac{1}{x_{0}} \operatorname{sech}\left(\frac{s-y_{0}}{\sqrt{1+a^{2}}}\right), a \ln \left(\frac{1}{x_{0}} \operatorname{sech}\left(\frac{s-y_{0}}{\sqrt{1+a^{2}}}\right)\right)\right)
$$

$s \in \mathbb{R}$, which are complete, where $x_{0}, x_{1}, y_{0}$ are integration constants. Therefore, the surface $M(f)$ is complete with constant negative Gaussian curvature $K$ with $-1<K<0$.

By Proposition 4.1 and Corollary 4.3 it is seen that the vertical graph surfaces $M(f)$ defined by $f(x, y)=$ $c=$ constant and $f(x, y)=a \ln y$ are the only complete and entire surfaces invariant by parabolic translation in $\mathbb{H}^{2} \times \mathbb{R}$ with constant negative Gaussian curvature. For $f(x, y)=c, M(f)$ has $K_{e x t}=0$ and $K=-1$, and for $f(x, y)=a \ln y, M(f)$ has $K_{\text {ext }}=0$ and $K=-1 /\left(1+a^{2}\right)$.

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## Author's contributions

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