

APPLICATION OF THE OPERATOR $\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix}; q, fD_q \right)$ FOR THE POLYNOMIALS $Y_n(a, b, c; d, e; x, y|q)$

HUSAM L. SAAD¹, RASHA H. JABER¹, §

ABSTRACT. In this paper, we construct the exponential operator $\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix}; q, fD_q \right)$ that has five parameters a, b, c, d, e and we define a more general polynomials $Y_n(a, b, c; d, e; x, y|q)$, in which case, the bivariate Rogers-Szegö polynomials $h_n(x, y|q)$ become special cases of $Y_n(a, b, c; d, e; x, y|q)$. Furthermore, we involve the operator's technique to give an elegant proof for the generating function with its extension, Mehler's formula with its extension, and Rogers formula for the polynomials $Y_n(a, b, c; d, e; x, y|q)$. As well as, we present some special values for the parameters a, b, c, d, e that will be inserted in the identities of $Y_n(a, b, c; d, e; x, y|q)$ in order to establish the generating function and its extension, Mehler's formula and its extension, and the Rogers formula for $h_n(x, y|q)$.

Keywords: The bivariate Rogers-Szegö polynomials, the generating function, Mehler's formula, Rogers formula.

AMS Subject Classification: 05A30, 33D45.

1. INTRODUCTION

In this paper we will use the standard notations for basic hypergeometric series given in [6], we assume that $|q| < 1$.

The q -shifted factorial is defined by

$$(a; q)_n = \begin{cases} 1, & \text{if } n = 0, \\ \prod_{k=0}^{n-1} (1 - aq^k), & \text{if } n = 1, 2, \dots \end{cases}$$

We define

$$(a; q)_\infty = \prod_{k=0}^{\infty} (1 - aq^k).$$

¹ Basrah University, College of Science, Department of Mathematics, Iraq.
 e-mail: hus6274@hotmail.com; ORCID: <https://orcid.org/0000-0001-8923-4759>.
 e-mail: rasharhadi2012@gmail.com; ORCID: <https://orcid.org/0000-0002-5385-8612>.

§ Manuscript received: April 06, 2020; accepted: September 01, 2020.

TWMS Journal of Applied and Engineering Mathematics, Vol.12, No.2 © Işık University, Department of Mathematics, 2022; all rights reserved.

The following notation is used for the multiple q -shifted factorials:

$$\begin{aligned}(a_1, a_2, \dots, a_m; q)_n &= (a_1; q)_n (a_2; q)_n \cdots (a_m; q)_n, \quad n = 0, 1, 2, \dots \\ (a_1, a_2, \dots, a_m; q)_\infty &= (a_1; q)_\infty (a_2; q)_\infty \cdots (a_m; q)_\infty.\end{aligned}$$

The generalized basic hypergeometric series is defined by [6]:

$${}_r\phi_s \left(\begin{matrix} a_1, \dots, a_r \\ b_1, \dots, b_s \end{matrix}; q, x \right) = \sum_{n=0}^{\infty} \frac{(a_1, \dots, a_r; q)_n}{(q, b_1, \dots, b_s; q)_n} \left[(-1)^n q^{\binom{n}{2}} \right]^{1+s-r} x^n,$$

The case $r = s + 1$ is the most important class of series

$${}_{s+1}\phi_s \left(\begin{matrix} a_1, \dots, a_{s+1} \\ b_1, \dots, b_s \end{matrix}; q, x \right) = \sum_{n=0}^{\infty} \frac{(a_1, \dots, a_{s+1}; q)_n}{(q, b_1, \dots, b_s; q)_n} x^n, \quad |x| < 1.$$

The q -binomial coefficient is defined by

$$\begin{bmatrix} n \\ k \end{bmatrix} = \begin{cases} \frac{(q; q)_n}{(q; q)_k (q; q)_{n-k}}, & \text{if } 0 \leq k \leq n; \\ 0, & \text{otherwise.} \end{cases}$$

One of the most important identities is the Cauchy identity

$$\sum_{n=0}^{\infty} \frac{(a; q)_n}{(q; q)_n} x^n = \frac{(ax; q)_\infty}{(x; q)_\infty}, \quad |x| < 1. \quad (1)$$

Euler found the following special case of Cauchy identity:

$$\sum_{n=0}^{\infty} \frac{x^n}{(q; q)_n} = \frac{1}{(x; q)_\infty}, \quad |x| < 1. \quad (2)$$

The following identity is the q -Chu-Vandermonde summation formula:

$${}_2\phi_1 \left(\begin{matrix} q^{-n}, b \\ c \end{matrix}; q, q \right) = \frac{(c/b; q)_n}{(c; q)_n} b^n. \quad (3)$$

The q -differential operator D_q is the one defined by [4]

$$D_q \{f(x)\} = \frac{f(x) - f(xq)}{x}.$$

The Leibniz rule for D_q is [10]

$$D_q^n \{f(x)g(x)\} = \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} q^{k(k-n)} D_q^k \{f(x)\} D_q^{n-k} \{g(xq^k)\}. \quad (4)$$

The following identities are easy to verify:

$$D_q^k \{x^n\} = \frac{(q; q)_n}{(q; q)_{n-k}} x^{n-k}. \quad (5)$$

$$D_q^k \left\{ \frac{1}{(xt; q)_\infty} \right\} = \frac{t^k}{(xt; q)_\infty}, \quad |x| < 1. \quad (6)$$

Based on the Euler identity (2), Chen and Liu [4] defined the q -exponential operator $T(bD_q)$ as follows:

$$T(bD_q) = \sum_{n=0}^{\infty} \frac{(bD_q)^n}{(q; q)_n}.$$

They used the q -exponential operator $T(bD_q)$ to derive the generating function, Mehler's formula and Rogers formula for classical Rogers-Szegö polynomials $h_n(x|q)$ which is defined by

$$h_n(x|q) = \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} x^k.$$

The Cauchy polynomials is defined by [7, 8]

$$P_k(x, y) = \begin{cases} (x - y)(x - qy) \cdots (x - yq^{k-1}), & \text{if } k > 0, \\ 1, & \text{if } k = 0. \end{cases}$$

In 2003, Chen *et. al.* [3] constructed the homogenous q -difference operator D_{xy} as follows:

$$D_{xy}\{f(x, y)\} = \frac{f(x, q^{-1}y) - f(qx, y)}{x - q^{-1}y}.$$

Based on the operator D_{xy} , they construct the following homogeneous q -shift operator

$$\mathbb{E}(D_{xy}) = \sum_{n=0}^{\infty} \frac{D_{xy}^n}{(q; q)_n}.$$

Also, they defined the bivariate Rogers-Szegö polynomials as follows:

$$h_n(x, y|q) = \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} P_k(x, y).$$

By using the homogeneous q -shift operator $E(D_{xy})$, they derived the generating function for $h_n(x, y|q)$

$$\sum_{n=0}^{\infty} h_n(x, y|q) \frac{t^n}{(q; q)_n} = \frac{(yt; q)_{\infty}}{(t, xt; q)_{\infty}}, \tag{7}$$

provided that $\max\{|t|, |xt|\} < 1$.

In 2007, Chen *et. al.* [5] used the q -exponential operator $T(bD_q)$ and the homogeneous q -shift operator $E(D_{xy})$ to derive Mehler's formula and Rogers formula for the polynomials $h_n(x, y|q)$.

In 2009, Saad and Sukhi [11] observed that $h_n(x, y|q)$ can be rewritten in the form

$$h_n(x, y|q) = \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} (y; q)_k x^{n-k}. \tag{8}$$

In 2013, Saad and Sukhi [12] defined the q -exponential operator $R(bD_q)$ as follows:

$$R(bD_q) = \sum_{k=0}^{\infty} \frac{(-1)^k q^{\binom{k}{2}}}{(q; q)_k} (bD_q)^k.$$

By using this operator, they derived Mehler's formula and Rogers formula for the polynomials $h_n(x, y|q)$.

Based on the q -Chu-Vandermonde summation formula (3), Zhang and Yang [14] considered the finite q -exponential operator with two parameters

$${}_2\mathcal{T}_1 \left[\begin{matrix} q^{-N}, v \\ w \end{matrix} ; q, tD_q \right] = \sum_{n=0}^N \frac{(q^{-N}, v; q)_n}{(q, w; q)_n} (tD_q)^n.$$

Inspired by the basic hypergeometric series ${}_2\phi_1$, Li and Tan [9] introduced the generalized q -exponential operator with three parameters

$$\mathbb{T} \left[\begin{matrix} u, v \\ w \end{matrix} \middle| q; tD_q \right] = \sum_{n=0}^{\infty} \frac{(u, v; q)_n}{(q, w; q)_n} (tD_q)^n.$$

Our work embraces four major parts that can be evidently organized as follows: In the first part, we set up the exponential operator $\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, fD_q \right)$ and then we define the polynomials $Y_n(a, b, c; d, e; x, y|q)$ which generalizes the the bivariate Rogers-Szegő polynomials $h_n(x, y|q)$. Then, we proceed further to demonstrate three factors in the polynomials which are the generating function with its extension, Mehler's formula with its extension, and Rogers formula for the polynomials $Y_n(a, b, c; d, e; x, y|q)$ by using an appropriate operator. In the final step, we employ some special values for the parameters a, b, c, d, e of the operator ϕ that would be utilized in the identities of $Y_n(a, b, c; d, e; x, y|q)$ to obtain the generating function and its extension, Mehler's formula and its extension, and the Rogers formula for $h_n(x, y|q)$.

2. THE q -EXPONENTIAL OPERATOR ϕ AND ITS IDENTITIES

We define the q -exponential operator with five parameters as follows:

$$\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, fD_q \right) = \sum_{n=0}^{\infty} \frac{(a, b, c; q)_n}{(q, d, e; q)_n} (fD_q)^n. \quad (9)$$

The finite q -exponential operator with two parameters ${}_2\mathcal{F}_1 \left[\begin{matrix} q^{-N}, v \\ w \end{matrix} ; q, tD_q \right]$ defined by Zhang and Yang [14] can be considered as special case of our operator for $a = q^{-N}$, $b = v$, $d = w$ and $c = e = 0$. Also the generalized q -exponential operator with three parameters $\mathbb{T} \left[\begin{matrix} u, v \\ w \end{matrix} \middle| q; tD_q \right]$ defined by Li and Tan [9] can be considered as special case of our operator for $a = u$, $b = v$, $c = 0$, $d = w$, $e = 0$ and $f = t$. In this section, we give some operator identities that will be used later to give a proof operator for some identities.

Lemma 2.1. *We have*

$$\begin{aligned} \phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, fD_q \right) \left\{ \frac{1}{(xt, xs; q)_{\infty}} \right\} &= \frac{1}{(xt, xs; q)_{\infty}} \\ &\times \sum_{k=0}^{\infty} \sum_{j=0}^{\infty} \frac{(a, b, c; q)_{k+j}}{(d, e; q)_{k+j}} \frac{(xt; q)_j}{(q; q)_k} (fs)^j (ft)^k, \end{aligned} \quad (10)$$

provided that $\max\{|xs|, |xt|\} < 1$.

Proof. By the definition of the operator $\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, fD_q \right)$, we have

$$\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, fD_q \right) \left\{ \frac{1}{(xt, xs; q)_{\infty}} \right\} = \sum_{k=0}^{\infty} \frac{(a, b, c; q)_k}{(c, d; q)_k} f^k D_q^k \left\{ \frac{1}{(xt, xs; q)_{\infty}} \right\}$$

By using Leibniz rule (4), we have

$$\begin{aligned}
 & \phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, fD_q \right) \left\{ \frac{1}{(xt, xs; q)_\infty} \right\} \\
 &= \sum_{k=0}^{\infty} \frac{(a, b, c; q)_k}{(q, d, e; q)_k} f^k \sum_{j=0}^k \begin{bmatrix} k \\ j \end{bmatrix} q^{j(j-k)} D_q^j \left\{ \frac{1}{(xs; q)_\infty} \right\} D_q^{k-j} \left\{ \frac{1}{(xtq^j; q)_\infty} \right\} \\
 &= \sum_{k=0}^{\infty} \frac{(a, b, c; q)_k}{(q, d, e; q)_k} f^k \sum_{j=0}^k \begin{bmatrix} k \\ j \end{bmatrix} q^{j(j-k)} \frac{s^j}{(xs; q)_\infty} \frac{(q^j t)^{k-j}}{(xtq^j; q)_\infty} \quad (\text{by using (6)}) \\
 &= \sum_{k=0}^{\infty} \frac{(a, b, c; q)_k}{(d, e; q)_k} f^k \sum_{j=0}^k \frac{s^j t^{k-j} (xt, q)_j}{(q; q)_{k-j} (q; q)_j (xs, xt; q)_\infty} \\
 &= \frac{1}{(xt, xs; q)_\infty} \sum_{k=0}^{\infty} \sum_{j=0}^{\infty} \frac{(a, b, c; q)_{k+j}}{(d, e; q)_{k+j} (q; q)_k} \frac{(xt; q)_j}{(q; q)_j} (fs)^j (ft)^k.
 \end{aligned}$$

□

Setting $s = 0$ in (10), we get the following corollary:

Corollary 2.1.

$$\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, fD_q \right) \left\{ \frac{1}{(xt; q)_\infty} \right\} = \frac{1}{(xt; q)_\infty} {}_3\phi_2 \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, ft \right), \tag{11}$$

provided that $\max\{|xt|, |ft|\} < 1$.

Lemma 2.2. For a nonnegative integer n , we have

$$\begin{aligned}
 & \phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, fD_q \right) \left\{ \frac{x^n}{(xt; q)_\infty} \right\} = \frac{x^n}{(xt; q)_\infty} \\
 & \sum_{k=0}^{\infty} \sum_{j=0}^n \begin{bmatrix} n \\ j \end{bmatrix} \frac{(a, b, c; q)_{k+j} (xt; q)_j (ft)^k (f/x)^j}{(d, e; q)_{k+j} (q; q)_k}, \tag{12}
 \end{aligned}$$

provided that $|xt| < 1$.

Proof. From definition of the operator $\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, fD_q \right)$, we have

$$\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, fD_q \right) \left\{ \frac{x^n}{(xt; q)_\infty} \right\} = \sum_{k=0}^{\infty} \frac{(a, b, c; q)_k}{(q, d, e; q)_k} f^k D^k \left\{ \frac{x^n}{(xt; q)_\infty} \right\}.$$

By using Leibniz rule (4), we have

$$\begin{aligned}
& \sum_{k=0}^{\infty} \frac{(a, b, c; q)_k}{(q, d, e; q)_k} f^k D^k \left\{ \frac{x^n}{(xt; q)_{\infty}} \right\} \\
&= \sum_{k=0}^{\infty} \frac{(a, b, c; q)_k}{(q, d, e; q)_k} f^k \sum_{j=0}^k \begin{bmatrix} k \\ j \end{bmatrix} q^{j(j-k)} D^j \{x^n\} D^{k-j} \left\{ \frac{1}{(q^j xt; q)_{\infty}} \right\} \\
&= \sum_{k=0}^{\infty} \frac{(a, b, c; q)_k}{(q, d, e; q)_k} f^k \sum_{j=0}^k \begin{bmatrix} k \\ j \end{bmatrix} q^{j(j-k)} \frac{(q; q)_n}{(q; q)_{n-j}} x^{n-j} \frac{(q^j t)^{k-j}}{(q^j xt; q)_{\infty}} \quad (\text{by using (5) and (6)}) \\
&= \sum_{k=0}^{\infty} \frac{(a, b, c; q)_k}{(d, e; q)_k} f^k \sum_{j=0}^k \begin{bmatrix} n \\ j \end{bmatrix} x^{n-j} t^{k-j} \frac{1}{(q^j xt; q)_{\infty} (q; q)_{k-j}} \\
&= \sum_{k=0}^{\infty} \sum_{j=0}^n \frac{(a, b, c; q)_{k+j}}{(d, e; q)_{k+j}} f^{k+j} \begin{bmatrix} n \\ j \end{bmatrix} x^{n-j} t^k \frac{(xt, q)_j}{(xt; q)_{\infty} (q; q)_k} \\
&= \frac{x^n}{(xt; q)_{\infty}} \sum_{k=0}^{\infty} \sum_{j=0}^n \begin{bmatrix} n \\ j \end{bmatrix} \frac{(a, b, c; q)_{k+j} (xt; q)_j (ft)^k (f/x)^j}{(d, e; q)_{k+j} (q; q)_k}.
\end{aligned}$$

□

3. THE GENERATING FUNCTION FOR $Y_n(a, b, c, d, e, f; q; x)$

We define the following polynomials:

$$Y_n(a, b, c; d, e; x, y|q) = \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} \frac{(a, b, c; q)_k}{(d, e; q)_k} y^k x^{n-k}.$$

The bivariate Rogers-Szegő polynomials $h_n(x, y|q)$ can be regarded as special case of the polynomials $Y_n(a, b, c; d, e; x, y|q)$ for $b = c = d = e = 0$, $y = 1$ and then $a = y$. Setting $b = c = d = e = 0$ and exchange x and y , we get the generalized Hahn polynomials [1]. In this section, we provide a working guide for the generating function and its extension for $Y_n(a, b, c; d, e; x, y|q)$. Then we give some parameter values to get the generating function and its extension for $h_n(x, y|q)$.

The following result is easy to verify:

$$\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix}; q, yD_q \right) \{x^n\} = Y_n(a, b, c; d, e; x, y|q). \quad (13)$$

Theorem 3.1. (The generating function for $Y_n(a, b, c; d, e; x, y|q)$). *We have*

$$\sum_{n=0}^{\infty} Y_n(a, b, c; d, e; x, y|q) \frac{t^n}{(q; q)_n} = \frac{1}{(xt; q)_{\infty}} {}_3\phi_2 \left(\begin{matrix} a, b, c \\ d, e \end{matrix}; q, yt \right), \quad (14)$$

provided that $\max\{|xt|, |ft|\} < 1$.

Proof.

$$\begin{aligned} & \sum_{n=0}^{\infty} Y_n(a, b, c; d, e; x, y|q) \frac{t^n}{(q; q)_n} \\ &= \sum_{n=0}^{\infty} \phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, yD_q \right) \{x^n\} \frac{t^n}{(q; q)_n} \quad (\text{by using (13)}) \\ &= \phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, yD_q \right) \left\{ \frac{1}{(xt; q)_{\infty}} \right\} \quad (\text{by using (2)}) \\ &= \frac{1}{(xt; q)_{\infty}} {}_3\phi_2 \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, yt \right). \quad (\text{by using (11)}) \end{aligned}$$

□

Setting $b = c = d = e = 0, y = 1$ and then $a = y$ in (14) and by using (8) and (1), we recover the generating function for the polynomials $h_n(x, y|q)$ (7).

Theorem 3.2. (Extension of generating function of $Y_n(a, b, c; d, e; x, y|q)$)

$$\begin{aligned} & \sum_{n=0}^{\infty} Y_{n+m}(a, b, c; d, e; x, y|q) \frac{t^n}{(q; q)_n} \\ &= \frac{x^m}{(xt; q)_{\infty}} \sum_{k=0}^{\infty} \sum_{j=0}^m \begin{bmatrix} m \\ j \end{bmatrix} \frac{(a, b, c; q)_{k+j} (xt; q)_j (yt)^k (y/x)^j}{(d, e; q)_{k+j} (q; q)_k}. \end{aligned} \tag{15}$$

Proof.

$$\begin{aligned} & \sum_{n=0}^{\infty} Y_{n+m}(a, b, c; d, e; x, y|q) \frac{t^n}{(q; q)_n} \\ &= \sum_{n=0}^{\infty} \phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, yD_q \right) \{x^{m+n}\} \frac{t^n}{(q; q)_n} \quad (\text{by using (13)}) \\ &= \phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, yD_q \right) \left\{ \frac{x^m}{(xt; q)_{\infty}} \right\} \quad (\text{by using 2}) \\ &= \frac{x^m}{(xt; q)_{\infty}} \sum_{k=0}^{\infty} \sum_{j=0}^m \begin{bmatrix} m \\ j \end{bmatrix} \frac{(a, b, c; q)_{k+j} (xt; q)_j (yt)^k (y/x)^j}{(d, e; q)_{k+j} (q; q)_k}. \quad (\text{by using 12}) \end{aligned}$$

□

Setting $b = c = d = e = 0, y = 1$ and then $a = y$ in the extension of generating function for the polynomials $Y_n(a, b, c; d, e; x, y|q)$ (15), we get the following extension of the generating function for the polynomials $h_n(x, y|q)$:

$$\sum_{n=0}^{\infty} h_{n+m}(x, y|q) \frac{t^n}{(q; q)_n} = \frac{x^m (yt; q)_{\infty}}{(xt, t; q)_{\infty}} {}_3\phi_1 \left(\begin{matrix} q^{-m}, xt, y \\ yt \end{matrix} ; q, q^m/x \right).$$

4. MEHLER'S FORMULA FOR $Y_n(a, b, c; d, e; x, y|q)$ AND $h_n(x, y|q)$

In this section we use the operator $\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix} ; q, yD_q \right)$ to derive Mehler's formula and its extension for the polynomials $Y_n(a, b, c; d, e; x, y|q)$. Then we give some special values to the parameters to obtain Mehler's formula and its extension for $h_n(x, y|q)$.

Theorem 4.1. (Mehler's formula for $Y_n(a, b, c; d, e; x, y|q)$). *We have*

$$\begin{aligned} & \sum_{n=0}^{\infty} Y_n(a, b, c; d, e; x, y|q) Y_n(a_1, b_1, c_1; d_1, e_1; u, v|q) \frac{t^n}{(q; q)_n} \\ &= \frac{1}{(xut; q)_{\infty}} \sum_{k=0}^{\infty} \frac{(a, b, c; q)_k}{(q, d, e; q)_k} (yut)^k \sum_{i=0}^{\infty} \sum_{j=0}^k \begin{bmatrix} k \\ j \end{bmatrix} \frac{(a_1, b_1, c_1; q)_{i+j} (xut; q)_j (vxt)^i (v/u)^j}{(d_1, e_1; q)_{i+j} (q; q)_i}. \end{aligned} \quad (16)$$

Proof.

$$\begin{aligned} & \sum_{n=0}^{\infty} Y_n(a, b, c; d, e; x, y|q) Y_n(a_1, b_1, c_1; d_1, e_1; u, v|q) \frac{t^n}{(q; q)_n} \\ &= \sum_{n=0}^{\infty} Y_n(a, b, c; d, e; x, y|q) \phi \left(\begin{matrix} a_1, b_1, c_1 \\ d_1, e_1 \end{matrix}; q, vD_q \right) \{u^n\} \frac{t^n}{(q; q)_n} \\ &= \phi \left(\begin{matrix} a_1, b_1, c_1 \\ d_1, e_1 \end{matrix}; q, vD_q \right) \left\{ \sum_{n=0}^{\infty} Y_n(a, b, c; d, e; x, y|q) \frac{(ut)^n}{(q; q)_n} \right\} \\ &= \phi \left(\begin{matrix} a_1, b_1, c_1 \\ d_1, e_1 \end{matrix}; q, vD_q \right) \left\{ \frac{1}{(xut; q)_{\infty}} {}_3\phi_2 \left(\begin{matrix} a, b, c \\ d, e \end{matrix}; q, yut \right) \right\} \quad (\text{by using (14)}) \\ &= \sum_{k=0}^{\infty} \frac{(a, b, c; q)_k}{(q, d, e; q)_k} (yt)^k \phi \left(\begin{matrix} a_1, b_1, c_1 \\ d_1, e_1 \end{matrix}; q, vD_q \right) \left\{ \frac{u^k}{(xut; q)_{\infty}} \right\}. \end{aligned}$$

Applying the operator $\phi \left(\begin{matrix} a_1, b_1, c_1 \\ d_1, e_1 \end{matrix}; q, vD_q \right)$ with respect to the parameter u and by using (12), we get the required result. \square

By using special values of the parameters in the Mehler's formula for the polynomials $Y_n(a, b, c; d, e; x, y|q)$ (16), we recover Mehler's formula for $h_n(x, y|q)$.

Corollary 4.1. (Mehler's formula for $h_n(x, y|q)$). *We have*

$$\sum_{n=0}^{\infty} h_n(x, y|q) h_n(u, v|q) \frac{t^n}{(q; q)_n} = \frac{(yt, xvt; q)_{\infty}}{(yut, t; q)_{\infty}} {}_3\phi_2 \left(\begin{matrix} y, xt, v/u \\ xvt, yt \end{matrix}; q, ut \right).$$

Proof. Setting $b = c = d = e = 0$, $y = 1$ and then $a = y$, and $h = u = v = w = 0$, $r = 1$ and then $g = v$ in Mehler's formula for $Y_n(a, b, c, d, e, f; x; q)$ (16), we get

$$\begin{aligned}
 & \sum_{n=0}^{\infty} h_n(x, y|q)h_n(u, v|q) \frac{t^n}{(q; q)_n} \\
 &= \frac{1}{(xut; q)_{\infty}} \sum_{k=0}^{\infty} \frac{(y; q)_k}{(q; q)_k} (ut)^k \sum_{i=0}^{\infty} \sum_{j=0}^k \begin{bmatrix} k \\ j \end{bmatrix} \frac{(v; q)_{i+j} (xut; q)_j}{(q; q)_i} (xt)^i (1/u)^j \\
 &= \frac{1}{(xut; q)_{\infty}} \sum_{i=0}^{\infty} \sum_{j=0}^{\infty} \sum_{k=0}^{\infty} \frac{(y; q)_{k+j}}{(q; q)_{k+j}} (ut)^{k+j} \frac{(q; q)_{k+j}}{(q; q)_k (q; q)_j} \frac{(v; q)_{i+j} (xut; q)_j}{(q; q)_i} (xt)^i (1/u)^j \\
 &= \frac{1}{(xut; q)_{\infty}} \sum_{j=0}^{\infty} \sum_{k=0}^{\infty} \frac{(y; q)_{k+j} (ut)^{k+j}}{(q; q)_k} \frac{(v, xut; q)_j (1/u)^j}{(q; q)_j} \sum_{i=0}^{\infty} \frac{(vq^j; q)_i (xt)^i}{(q; q)_i} \\
 &= \frac{1}{(xut; q)_{\infty}} \sum_{j=0}^{\infty} \sum_{k=0}^{\infty} \frac{(y; q)_{k+j} (ut)^{k+j}}{(q; q)_k} \frac{(v, xut; q)_j (1/u)^j}{(q; q)_j} \frac{(vxtq^j; q)_{\infty}}{(xt; q)_{\infty}} \quad (\text{by using (1)}) \\
 &= \frac{(xvt; q)_{\infty}}{(xut, xt; q)_{\infty}} \sum_{j=0}^{\infty} \frac{(v, xut, y; q)_j t^j}{(q, xvt; q)_j} \sum_{k=0}^{\infty} \frac{(yq^j; q)_k (ut)^k}{(q; q)_k} \\
 &= \frac{(xvt; q)_{\infty}}{(xut, xt; q)_{\infty}} \sum_{j=0}^{\infty} \frac{(v, xut, y; q)_j t^j}{(q, xvt; q)_j} \frac{(yutq^j; q)_{\infty}}{(ut; q)_{\infty}} \quad (\text{by using (1)}) \\
 &= \frac{(xvt, uty; q)_{\infty}}{(xut, xt, ut; q)_{\infty}} \sum_{j=0}^{\infty} \frac{(v, xut, y; q)_j t^j}{(q, xvt, yut; q)_j} \\
 &= \frac{(xvt, uty; q)_{\infty}}{(xut, xt, ut; q)_{\infty}} {}_3\phi_2 \left(\begin{matrix} v, y, xut \\ yut, xvt \end{matrix}; q, t \right). \tag{17}
 \end{aligned}$$

By using transformation of ${}_3\phi_2$ series [6, Appendix , Eq. (III.9)], we get

$${}_3\phi_2 \left(\begin{matrix} y, v, xut \\ xvt, yut \end{matrix}; q, t \right) = \frac{(ut, yt; q)_{\infty}}{(yut, t; q)_{\infty}} {}_3\phi_2 \left(\begin{matrix} y, xt, v/u \\ xvt, yt \end{matrix}; q, ut \right).$$

Substituting the above equation into (17), we get the required result. □

Theorem 4.2. (Extension of Mehler's formula for $Y_n(a, b, c, d, e, f; x; q)$)

$$\begin{aligned}
 & \sum_{n=0}^{\infty} Y_{n+m}(a, b, c; d, e; x, y|q)Y_n(a_1, b_1, c_1; d_1, e_1; u, v|q) \frac{t^n}{(q; q)_n} \\
 &= \frac{x^m}{(vtx; q)_{\infty}} \sum_{k=0}^{\infty} \sum_{j=0}^m \begin{bmatrix} m \\ j \end{bmatrix} \frac{(a, b, c; q)_{k+j} (y/x)^j (yvt)^k (vtx; q)_j}{(d, e; q)_{k+j} (q; q)_k} \\
 & \quad \times \sum_{i=0}^{\infty} \sum_{l=0}^k \begin{bmatrix} k \\ l \end{bmatrix} \frac{(a_1, b_1, c_1; q)_{i+l} (vtxq^j; q)_l (xvtq^j)^i (v/u)^l}{(d_1, e_1; q)_{l+i} (q; q)_i}. \tag{18}
 \end{aligned}$$

Proof.

$$\begin{aligned}
& \sum_{n=0}^{\infty} Y_{n+m}(a, b, c; d, e; x, y; q) Y_n(a_1, b_1, c_1; d_1, e_1; u, v; q) \frac{t^n}{(q; q)_n} \\
&= \sum_{n=0}^{\infty} Y_{n+m}(a, b, c; d, e; x, y; q) \phi \left(\begin{matrix} a_1, b_1, c_1 \\ d_1, e_1 \end{matrix}; q, vD_q \right) \{u^n\} \frac{t^n}{(q; q)_n} \quad (\text{by using (13)}) \\
&= \phi \left(\begin{matrix} a_1, b_1, c_1 \\ d_1, e_1 \end{matrix}; q, vD_q \right) \left\{ \sum_{n=0}^{\infty} Y_{n+m}(a, b, c; d, e; x, y; q) \frac{(ut)^n}{(q; q)_n} \right\} \\
&= \phi \left(\begin{matrix} a_1, b_1, c_1 \\ d_1, e_1 \end{matrix}; q, vD_q \right) \left\{ \frac{x^m}{(xut; q)_{\infty}} \sum_{k=0}^{\infty} \sum_{j=0}^m \begin{bmatrix} m \\ j \end{bmatrix} \frac{(a, b, c; q)_{k+j} (xut; q)_j (yut)^k (y/x)^j}{(d, e; q)_{k+j} (q; q)_k} \right\} \\
& \hspace{20em} (\text{by using (15)}) \\
&= z^m \sum_{k=0}^{\infty} \sum_{j=0}^m \frac{(a, b, c; q)_{k+j} (yt)^k (y/x)^j}{(d, e; q)_{k+j} (q; q)_k} \phi \left(\begin{matrix} a_1, b_1, c_1 \\ d_1, e_1 \end{matrix}; q, vD_q \right) \left\{ \frac{u^k}{(uxtq^j; q)_{\infty}} \right\} \\
&= x^m \sum_{k=0}^{\infty} \sum_{j=0}^m \begin{bmatrix} m \\ j \end{bmatrix} \frac{(a, b, c; q)_{k+j} (yt)^k (y/x)^j}{(d, e; q)_{k+j} (q; q)_k} \frac{u^k}{(uxtq^j; q)_{\infty}} \sum_{i=0}^{\infty} \sum_{l=0}^k \begin{bmatrix} k \\ l \end{bmatrix} \frac{(a_1, b_1, c_1; q)_{i+l}}{(d_1, e_1; q)_{l+i} (q; q)_i} \\
& \quad \times \frac{(uxtq^j; q)_l (vxtq^j)^i (v/u)^l}{(q; q)_i} \quad (\text{by using (12)}) \\
&= \frac{x^m}{(utx; q)_{\infty}} \sum_{k=0}^{\infty} \sum_{j=0}^m \begin{bmatrix} m \\ j \end{bmatrix} \frac{(a, b, c; q)_{k+j} (y/x)^j (ytu)^k (utx; q)_j}{(d, e; q)_{k+j} (q; q)_k} \\
& \quad \times \sum_{i=0}^{\infty} \sum_{l=0}^k \begin{bmatrix} k \\ l \end{bmatrix} \frac{(a_1, b_1, c_1; q)_{i+l} (utxq^j; q)_l (xvtq^j)^i (v/u)^l}{(d_1, e_1; q)_{l+i} (q; q)_i}.
\end{aligned}$$

□

Setting $a = y, b = c = d = e = 0, f = 1, z = x, g = v, h = u = v = w = 0, r = 1$ and $x = u$ in the extension of Mehler's formula for $Y_n(a, b, c, d, e, f; x; q)$ (18) and by using (8), we get the following extension of Mehler's formula for the polynomials $h_n(x, y|q)$:

$$\begin{aligned}
& \sum_{n=0}^{\infty} h_{n+m}(x, y|q) h_n(u, v|q) \frac{t^n}{(q; q)_n} \\
&= \frac{x^m (vxt, yut; q)_{\infty}}{(uxt, xt, ut; q)_{\infty}} \sum_{k=0}^{\infty} \sum_{j=0}^m \frac{(y; q)_{j+l} (uxt, xt; q)_j (v, xutq^j; q)_l (1/x)^j t^l}{(xvt, yut; q)_{j+l} (q; q)_l}.
\end{aligned}$$

5. THE ROGERS FORMULA FOR $Y_n(a, b, c; d, e; x, y|q)$ AND $h_n(x, y|q)$

In this section we use the operator $\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix}; q, yD_q \right)$ to derive Rogers formula for the polynomials $Y_n(a, b, c; d, e; x, y|q)$. Then we give some special values for the parameters in Rogers formula for polynomial $Y_n(a, b, c; d, e; x, y|q)$ to recover Rogers formula for $h_n(x, y|q)$.

Theorem 5.1. (The Rogers formula for $Y_n(a, b, c; d, e; x, y|q)$). We have

$$\begin{aligned} & \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} Y_{n+m}(a, b, c, d, e, f; x; q) \frac{t^n}{(q; q)_n} \frac{s^m}{(q; q)_m} \\ &= \frac{1}{(xt, xs; q)_{\infty}} \sum_{k=0}^{\infty} \sum_{j=0}^{\infty} \frac{(a, b, c; q)_{k+j} (xt; q)_j (ft)^k (fs)^j}{(d, e; q)_{k+j} (q; q)_k (q; q)_j}, \end{aligned} \tag{19}$$

provided that $\max\{|xt|, |xs|\} < 1$.

Proof.

$$\begin{aligned} & \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} Y_{n+m}(a, b, c, d, e, f; x; q) \frac{t^n}{(q; q)_n} \frac{s^m}{(q; q)_m} \\ &= \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} \phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix}; q, yD_q \right) \{x^{n+m}\} \frac{t^n}{(q; q)_n} \frac{s^m}{(q; q)_m} \\ &= \phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix}; q, yD_q \right) \left\{ \frac{1}{(xt, xs; q)_{\infty}} \right\}. \quad (\text{by using (2)}) \end{aligned}$$

By using (10), we get the required result. □

Setting $a = y, b = c = d = e = 0$ and $f = 1$ in the Rogers formula of $Y_n(a, b, c, d, e, f; q; x)$ (5.1), we recover the following Rogers formula for the bivariate Rogers-Szegő polynomials $h_n(x, y|q)$ [5]:

$$\sum_{n=0}^{\infty} \sum_{m=0}^{\infty} h_{n+m}(x, y|q) \frac{t^n}{(q; q)_n} \frac{s^m}{(q; q)_m} = \frac{(ys; q)_{\infty}}{(xs, s, xt; q)_{\infty}} {}_2\phi_1 \left(\begin{matrix} y, xs \\ ys \end{matrix}; q, t \right),$$

provided that $\max\{|s|, |xt|, |xs|\} < 1$.

6. CONCLUSIONS

- (1) The finite q -exponential operator ${}_2\mathcal{T}_1 \left[\begin{matrix} q^{-N}, v \\ w \end{matrix}; q, tD_q \right]$ and the generalized q -exponential operator $\mathbb{T} \left[\begin{matrix} u, v \\ w \end{matrix} | q; tD_q \right]$ are special cases of the operator $\phi \left(\begin{matrix} a, b, c \\ d, e \end{matrix}; q, yD_q \right)$.
- (2) We may give special values in polynomial identities for $Y_n(a, b, c; d, e; x, y|q)$ to obtain polynomial identities for $h_n(x, y|q)$ versus $a = y, b = 0, c = 0, d = 0, e = 0$ and $f = 1$ as seen in the generating function, Rogers formula and Mehler's formula.
- (3) Generalized Han polynomials [1] are a special case of our polynomial $Y_n(a, b, c; d, e; x, y|q)$ versus $b = c = d = e = 0, x = y$ and then $f = x$.
- (4) The operator proof is simpler than the classical proof.

Acknowledgement. We are deeply grateful to the referees for valuable comments that lead to an improvement of an earlier version.

REFERENCES

- [1] Abdhusein, M. A., (2015), The generalized Hahn polynomials, TWMS J. App. Eng. Math., 5, pp. 231-248.
- [2] Chen, V. Y. B. and Gu, N. S. S., (2008), The Cauchy operator for basic hypergeometric series, Adv. Appl. Math., 41, pp. 177-196.
- [3] Chen, W. Y. C., Fu, A. M. and Zhang, B. Y., The homogeneous q -difference operator, Adv. Appl. Math., 31, pp. 659-668.
- [4] Chen, W. Y. C. and Liu, Z. G., (1997), Parameter augmenting for basic hypergeometric series, II, J. Combin. Theory, Ser. A, 80, pp. 175-195.
- [5] Chen, W. Y. C., Saad, H. L. and Sun, L. H., (2007), The bivariate Rogers-Szegő polynomials, J. Phys. A: Math. Theor., 40, pp. 6071-6084.
- [6] Gasper, G. and Rahman, M., (2004), Basic Hypergeometric Series, 2nd ed., Cambridge University Press, Cambridge, MA.
- [7] Goldman, J. and Rota, G. C., (1970), On the foundations of combinatorial theory, IV: Finite vector spaces and Eulerian generating functions, Stud. Appl. Math., 49, pp. 239-258.
- [8] Goulden, I. P. and Jackson, D. M., (1983), Combinatorial Enumeration, John Wiley & Sons, New York.
- [9] Li, N. N. and Tan, W., (2016), Two generalized q -exponential operators and their applications, Advances in difference equations, 53, pp. 1-14.
- [10] Roman, S., (1985), More on the umbral calculus, with emphasis on the q -umbral calculus, J. Math. Anal. Appl., 107, pp. 222-254.
- [11] Saad, H. L. and Sukhi, A. A., (2010), Another Homogeneous q -difference Operator, Applied Mathematics and Computation, 215, pp. 4331-4339.
- [12] Saad, H. L. and Sukhi, A. A., (2013), The q -Exponential Operator, Appl. Math. Sci., 7, pp. 6369 – 6380.
- [13] Zhang, Z. Z. and Wang, J., (2005), Two operator identities and their applications to terminating basic hypergeometric series and q -integrals, J. Math. Anal. Appl., 312, pp. 653-665.
- [14] Zhang, Z. Z. and Yang, J. Z., (2010), Finite q -exponential operators with two parameters and their applications, Acta Mathematica Sinica, Chinese Series, 53, pp. 1007-1018.



Husam Luti Saad is a professor in the Department of Mathematics, College of Science, Basrah University, Iraq. He received his Ph.D. in mathematics from the Center for Combinatorics, Nankai University, China in 2005. His main area of interest is q -Series, q -Operators.



Rasha Hadi Jaber is an assistant lecturer in the Department of Mathematics, College of Science, Basrah University, Iraq. She completed her M.Sc. in Mathematics, from the Department of Mathematics, College of Science, Basrah University, Iraq. Her main area of interest is q -Series and q -Operators.